## Unit 6: Coordinates with Rover — Skill Builder 2: The Distance Formula

In this lesson, you will use the distance formula from coordinate Geometry to calculate the distance between two points and compare the Rover's measured distance against the calculated distance. **You will need a meter stick or metric tape measure for this lesson.

**Objectives:**

- Move to two different points
- Use a marker to draw the segment
- Use a function to compute the distance between two points and display the distance
- Measure the distance between the points
- Compute the error in the measurement versus the computation

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Recall the "Distance Formula", which is based on the Pythagorean Theorem:

$$d=\sqrt{(x2-x1)^2+(y2-y1)^2}$$

Based on the image to the right, this becomes the Python statement:

**d = sqrt((6 - 2)**2 + (4 - 1)**2)**

This evaluates to: **d = 5**

Can you find a 3-4-5 right triangle in the image?

1. Start a new Python Rover Coding project.

   Define a function called **dist** which takes four arguments (two pairs of coordinates) and will return the distance between the two points.

   The **def** function**()** template is found on **menu > Built-ins > Functions**.

   The body of the function consists of one calculation:

   $$d=\sqrt{(x2-x1)^2+(y2-y1)^2}$$

   and the **return** statement: **return d**

   **return** is found on **menu > Built-ins > Functions**

   Make sure these two statements are indented the same amount.

2. Below the function (after the **return** statement), begin the main program. Be sure your code is no longer indented. Write four **input()** statements (using copy and paste) to enter the coordinates of the two points. Create simple prompts for the inputs and use the **float()** function to convert the input result from a string to a decimal value. Only one of these four statements is shown to the right. We are using the variable **a** to store the first x-coordinate. Use **b**, **c**, and **d** for the other three coordinates.

3. After the four **input()** statements, make Rover drive to the first point. Pause there while you *insert a marker* in the Rover's marker holder to draw a line segment. Then continue driving to the second point. A good pause statement is:

**input( "press [enter] to continue.")**

The result of this input function does not assign any value to a variable because nothing is entered.

4. Now have the program evaluate the distance function using the coordinates of your two points:

**calculated_distance = dist(a, b, c, d)**

5. Use a ruler or tape measure to determine the length of the segment that Rover made.

   Add an **input()** statement to your program so that you can enter the **measured_distance**.

   Add **print()** statements to display the **two distance variables.**

   How does the measured distance compare to the calculated distance?

6. Calculate the percent error using the formula

   **(measured - calculated*)* / calculated * 100**

   and print the error.